

Simulations in graphene

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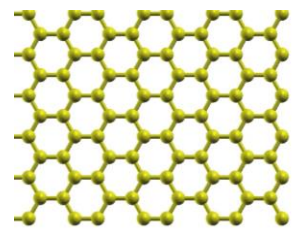
Greece



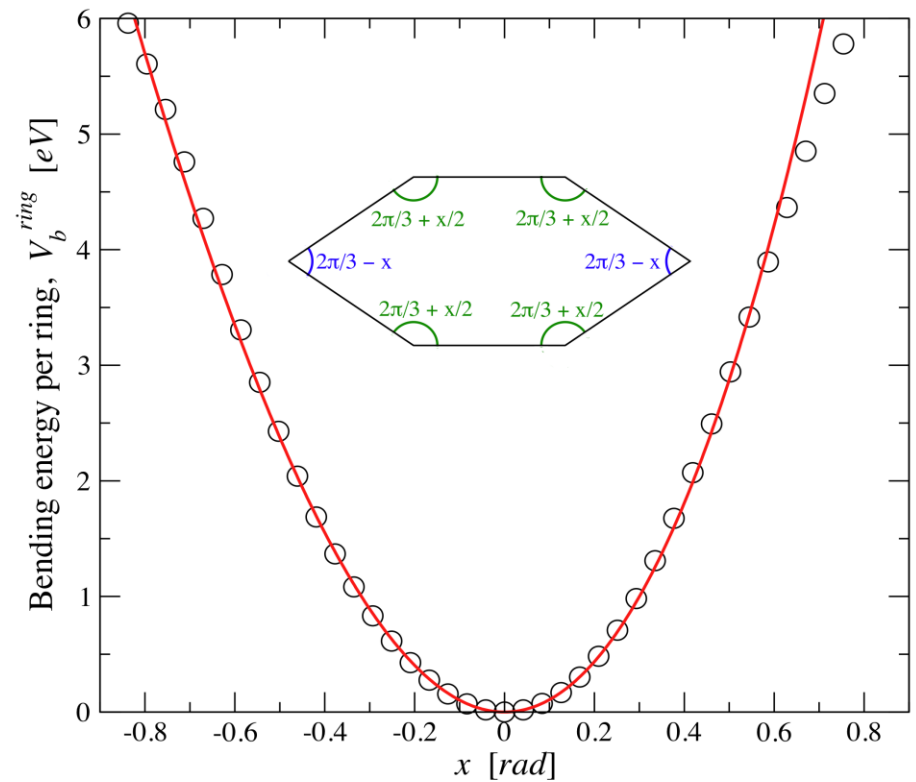
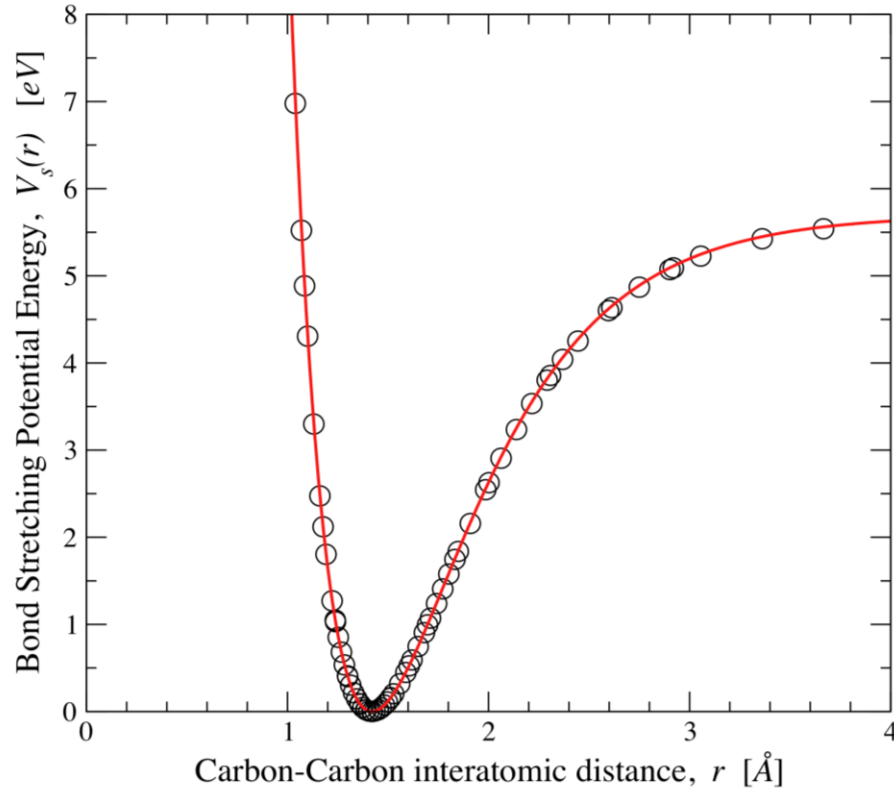
CRETE CENTER FOR
QUANTUM COMPLEXITY
AND NANOTECHNOLOGY



Atomistic simulations in graphene



In-plane **bond stretching** and **angle bending** interatomic potentials are derived using first principles methods (DFT) in appropriately deformed graphene configurations



Fitting with analytical expressions

$$V_s(r) = D \left(e^{-a(r-r_0)} - 1 \right)^2$$

$$D = 5.7 \text{ eV}, a = 1.96 \text{ \AA}^{-1}, r_0 = 1.42 \text{ \AA}$$

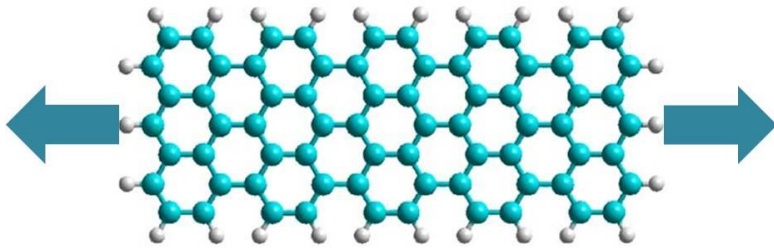
$$V_b(\varphi) = \frac{k}{2} \left(\varphi - \frac{2\pi}{3} \right)^2 - \frac{k'}{3} \left(\varphi - \frac{2\pi}{3} \right)^3$$

$$V_b^{\text{ring}} = \frac{3}{2} k x^2 + \frac{1}{2} k' x^3$$

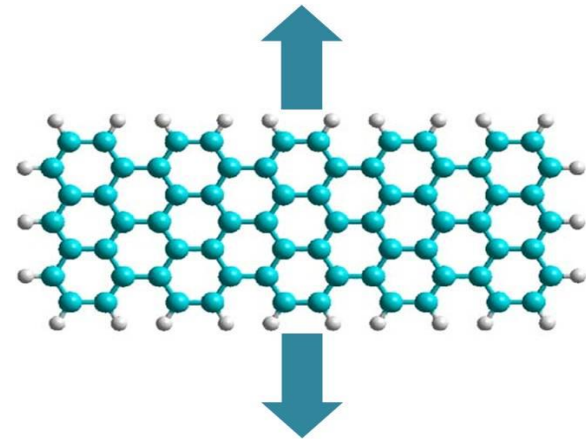
$$k = 7.0 \text{ eV/rad}^2, k' = 4 \text{ eV/rad}^3$$

Mechanical response: Application of various loads

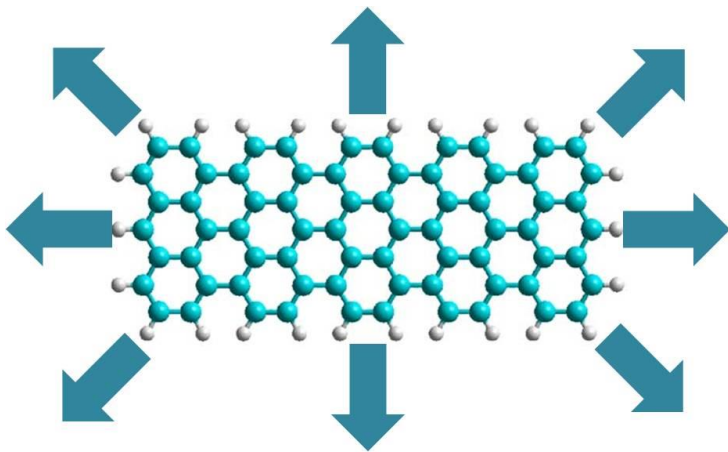
Uniaxial stress along the zigzag edge



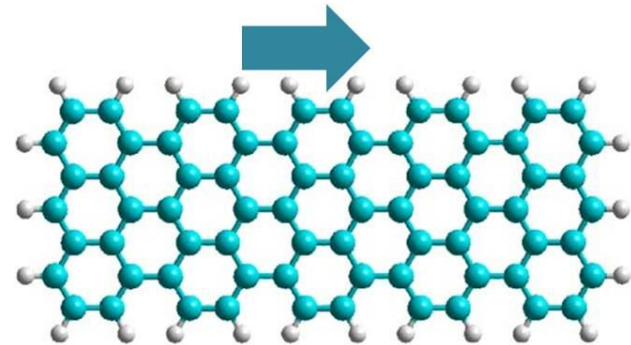
Uniaxial stress along the armchair edge



Hydrostatic pressure



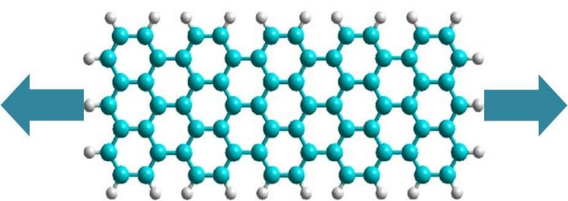
Shear stress along the armchair/zigzag edge



Equilibrium under the application of a uniaxial force

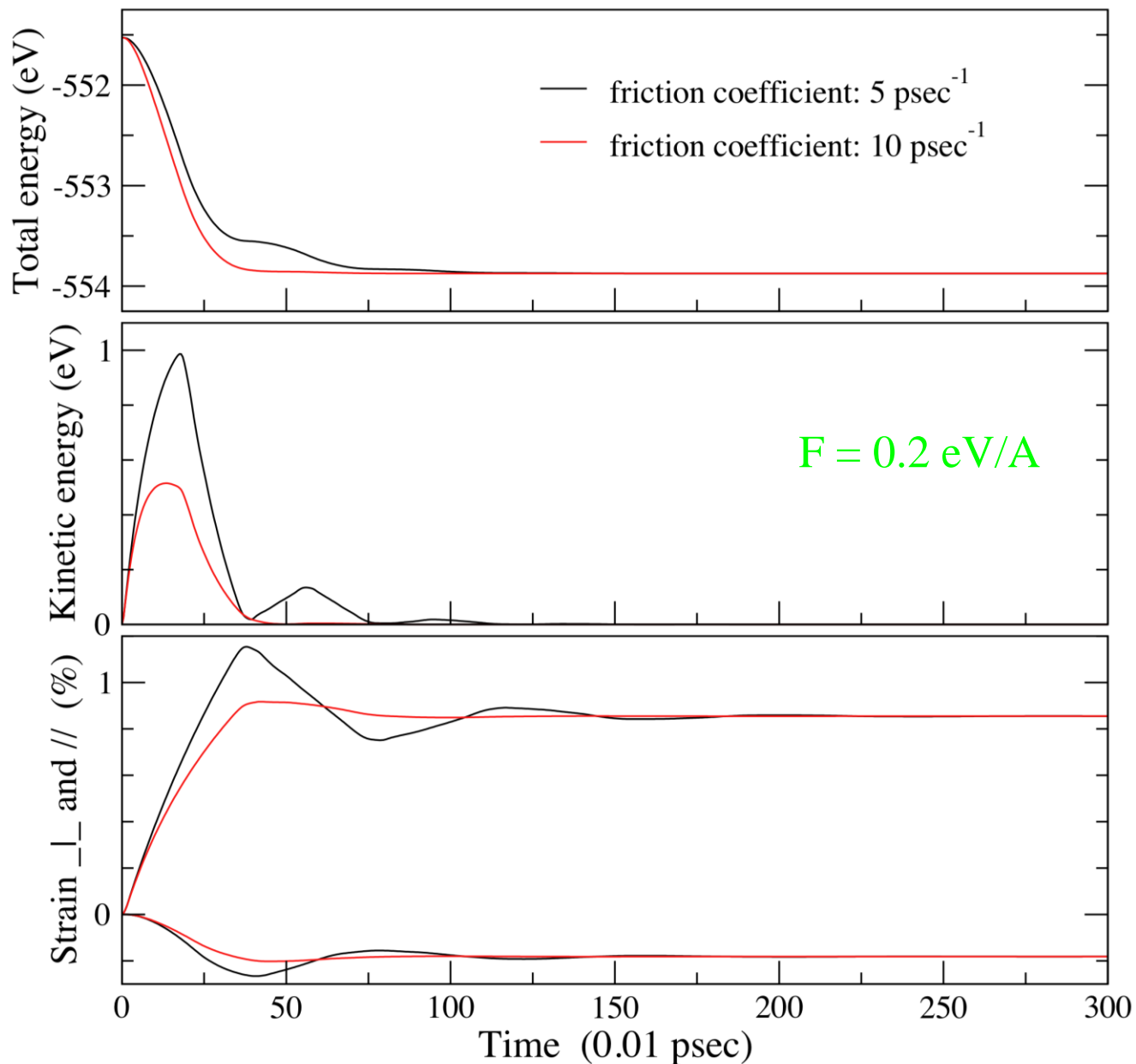
Start with the equilibrium structure of a graphene (without any force) containing 7482 or 17030 atoms

Apply a constant force at all atoms in the two edges



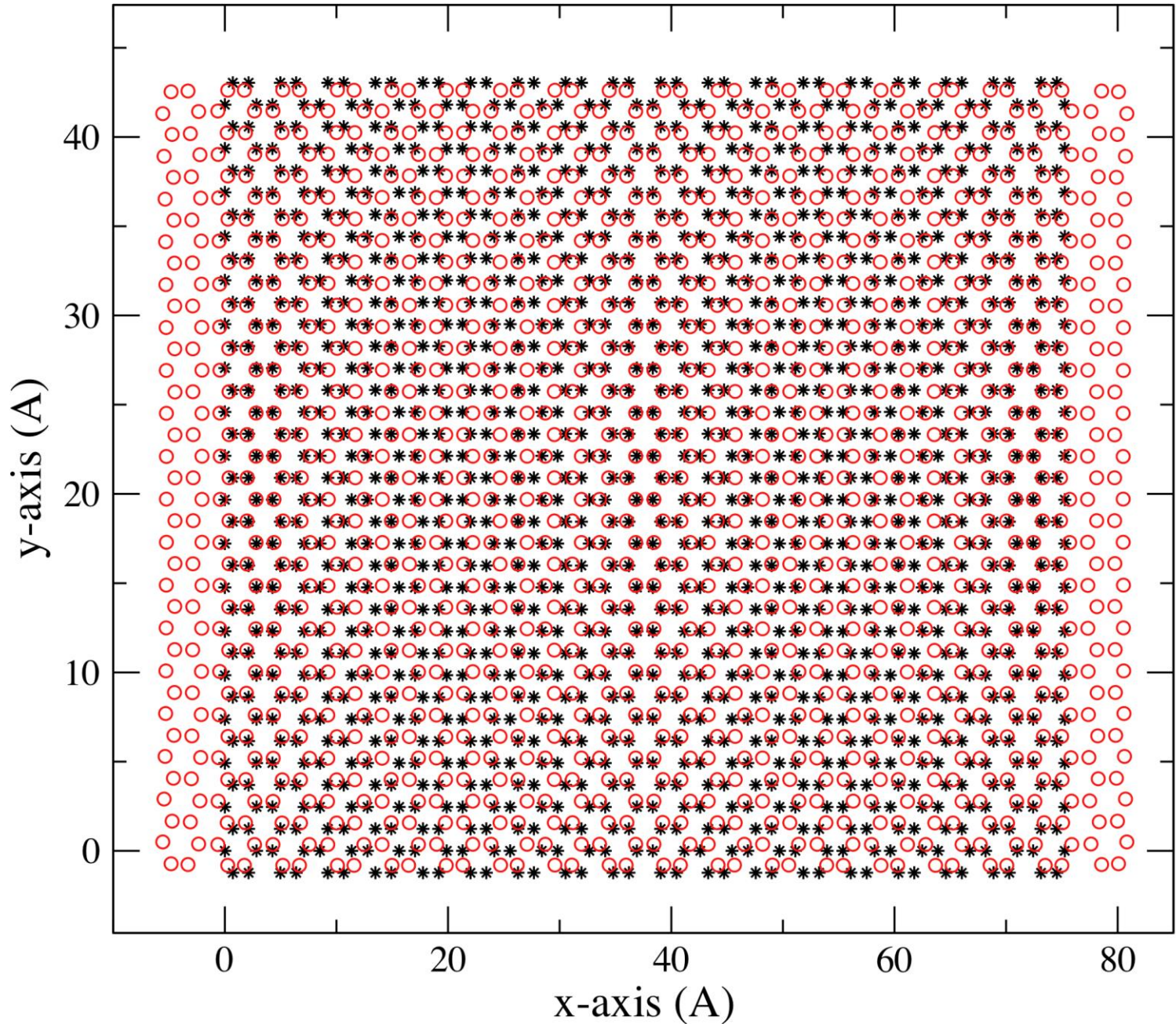
Follow with MD the evolution of the system, applying a friction term at each atom

The system goes to a new equilibrium compatible to the applied forces

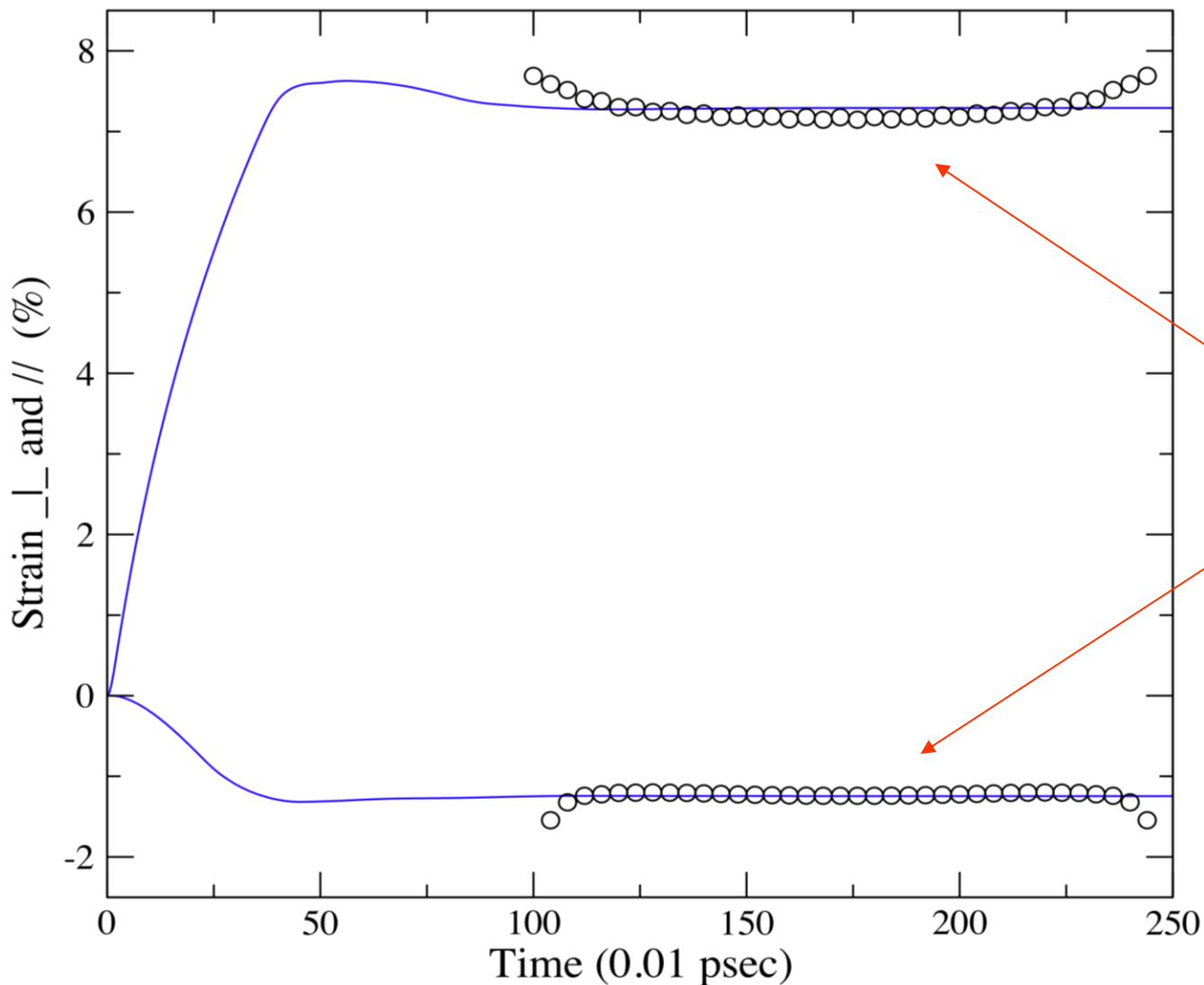
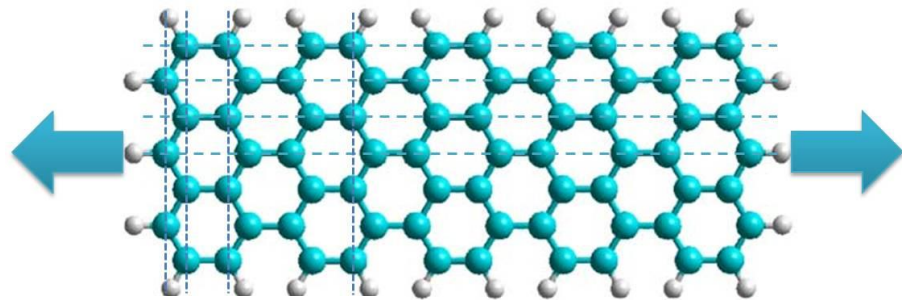


Equilibrium stretched structure

$F = 2.4 \text{ eV/\AA}$



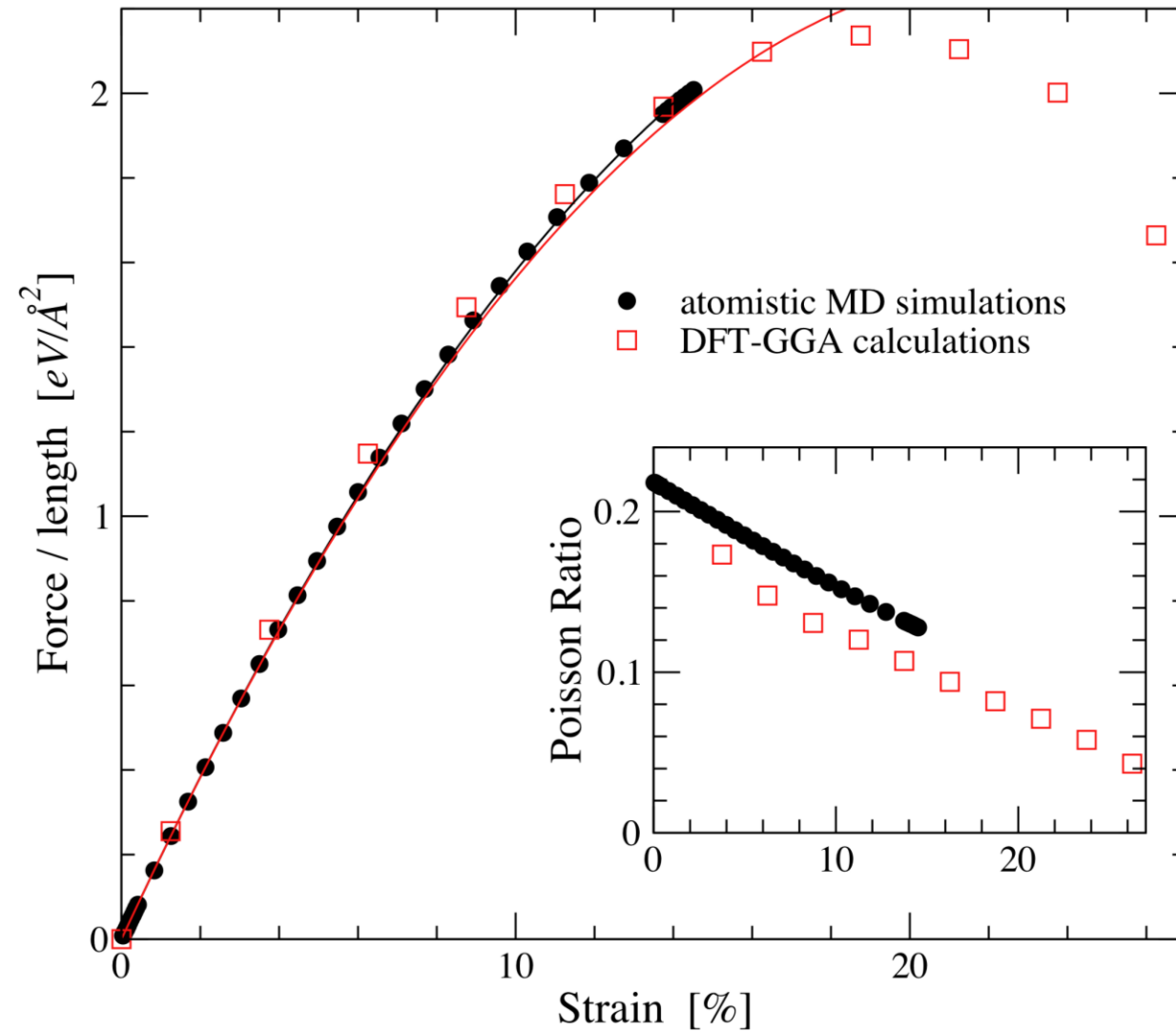
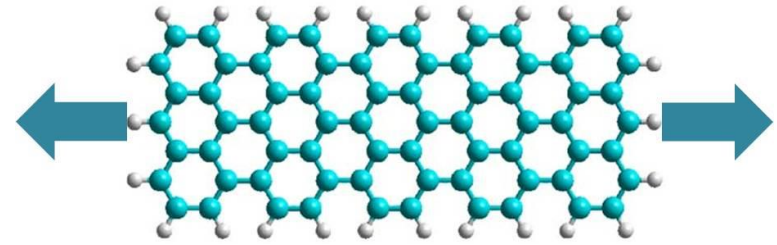
Strain distribution



Distribution of strains along the horizontal/vertical lines of the graphene structure (at the end of the simulation)

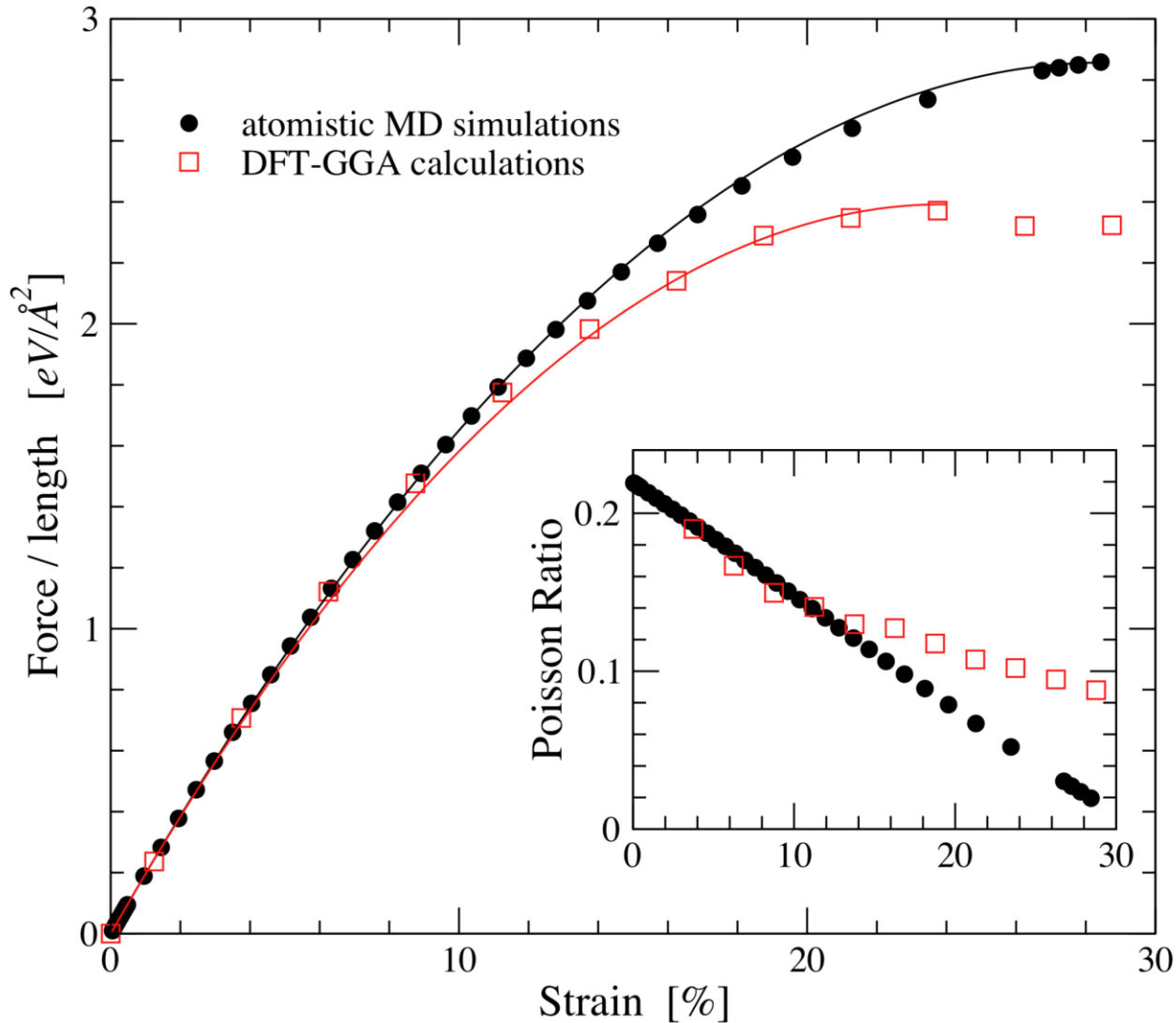
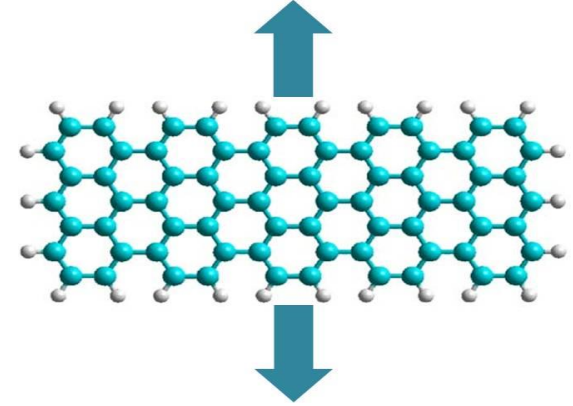
$$F = 1.5 \text{ eV/\AA}$$

Graphene uniaxial stress response I



Young Modulus
 $E_{2D}=320 \text{ N/m}$

Graphene uniaxial stress response II



Young Modulus
 $E_{2D}=320 \text{ N/m}$

Comparison of calculated elastic constants with experimental and other theoretical results

2d Elastic constant: $E_{2D} = 320 \text{ N/m}$

→ effective Young modulus $E_{\text{eff}} = E_{2D}/0.335\text{nm} = 0.96 \text{ TPa}$

Experimental estimate: $E_{2D} = 340 \pm 50 \text{ N/m}$

→ $E_{\text{eff}} = 1.0 \pm 0.1 \text{ TPa}$

Lee et al., *Science* **321**, 385 (2008)

Other theoretical results:

$E_{\text{eff}} = 1.05 \text{ TPa}$ (in both directions)

Liu, Ming, Li, *Phys. Rev. B* **76**, 064120 (2007)

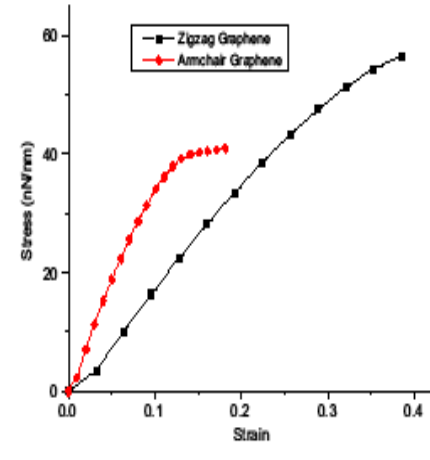
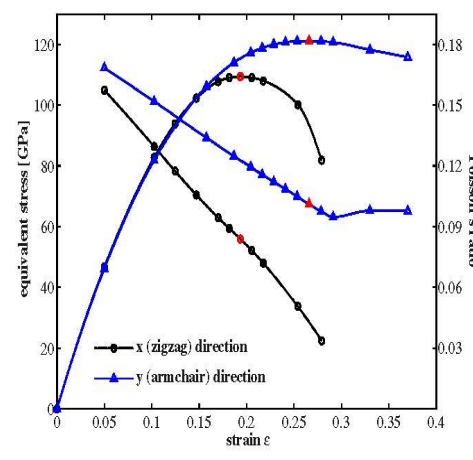
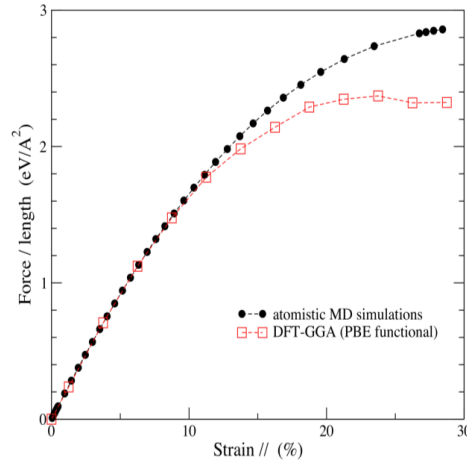
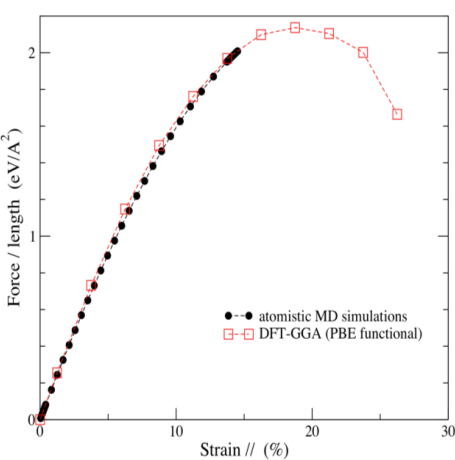
$E_{\text{eff}} = 1.05\text{-}1.06 \text{ TPa}$

Zakharchenko, Katsnelson, Fasolino, *Phys. Rev. Lett.* **102**, 046808 (2009)

$E_{\text{eff}} = 1.1 \text{ TPa}$ (0.6 TPa in the other direction)

Gao, Hao, *Physica E* **41**, 1561 (2009)

Values of E_{eff} in the range 0.5 – 3.5 TPa have been reported in the literature



Comparison of calculated intrinsic strength with experimental and other theoretical results

2d Intrinsic strength: $\sigma_{2D} = 39-45 \text{ N/m}$ (32-34 N/m in the other direction)

→ effective intrinsic strength $\sigma_{\text{eff}} = \sigma_{2D}/0.335\text{nm} = 120-130 \text{ GPa}$ (100 GPa)

Experimental estimate: $\sigma_{2D} = 42 \pm 4 \text{ N/m}$

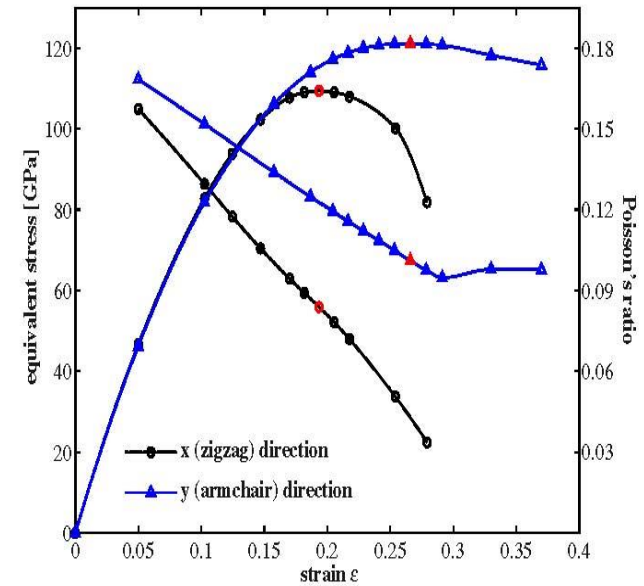
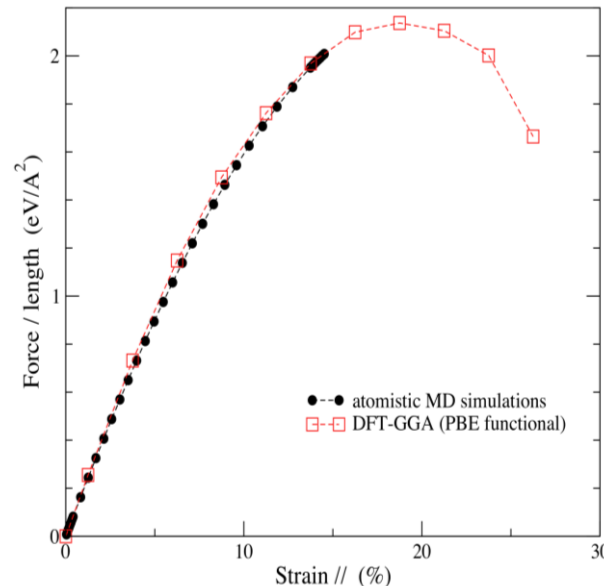
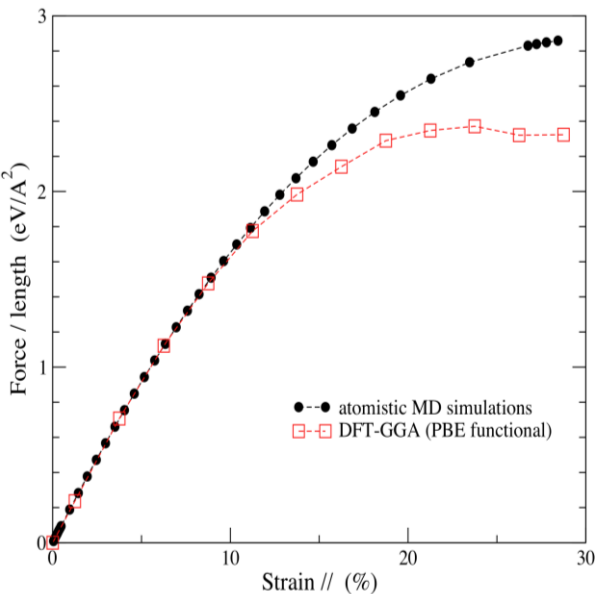
→ $\sigma_{\text{eff}} = 130 \pm 20 \text{ GPa}$

Lee et al., *Science* **321**, 385 (2008)

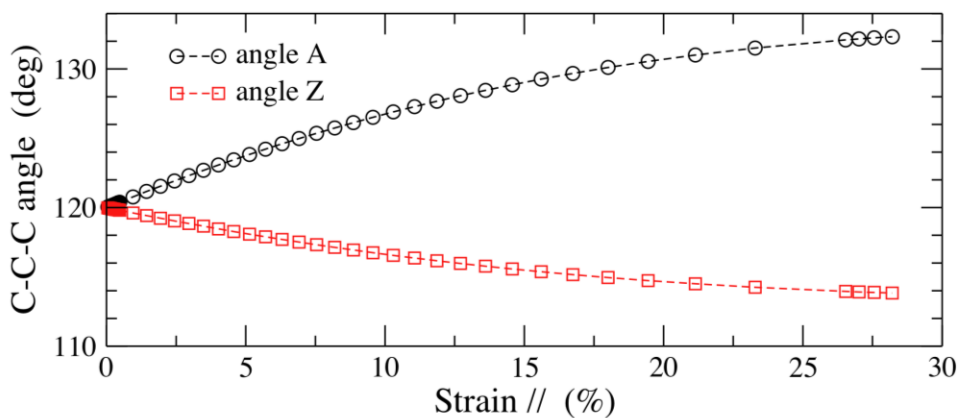
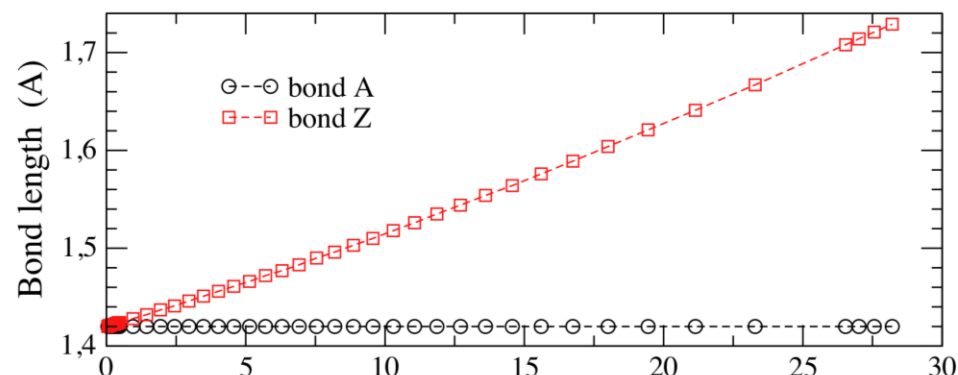
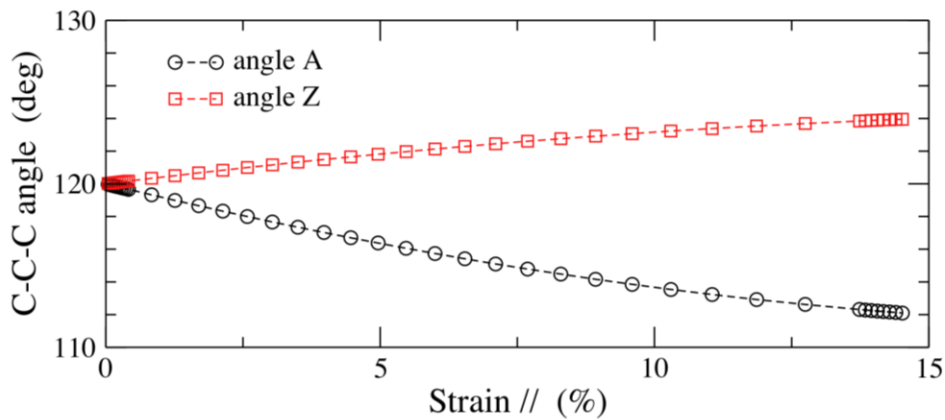
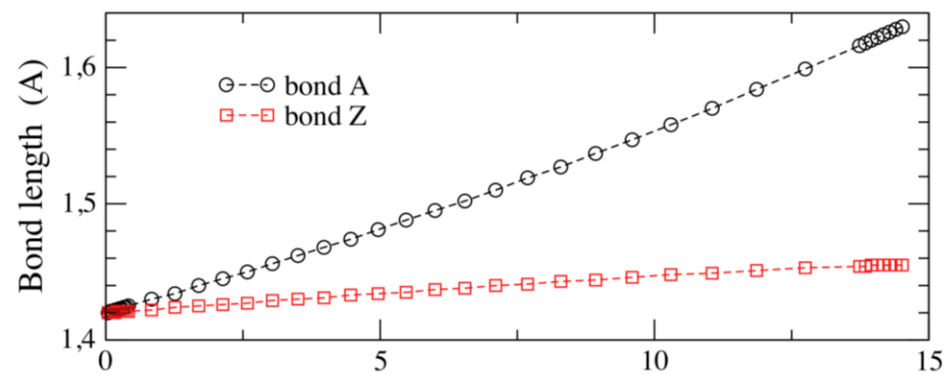
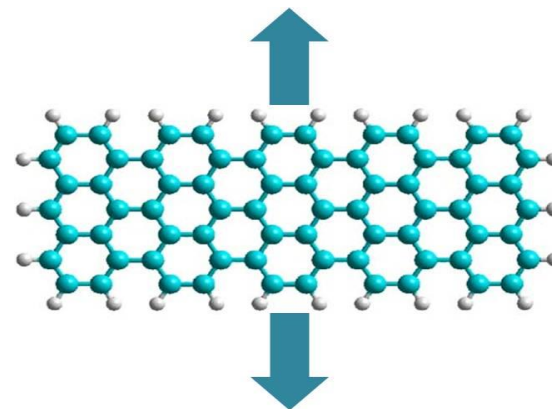
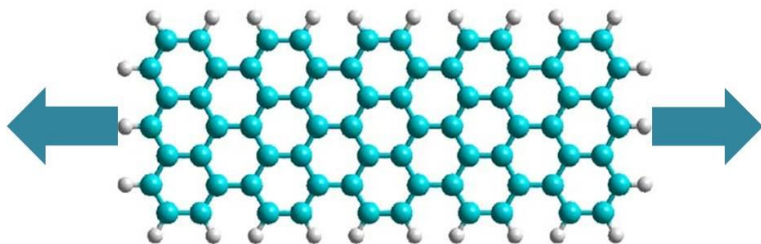
Other theoretical results:

$\sigma_{\text{eff}} = 121 \text{ GPa}$ (110 GPa in the other direction)

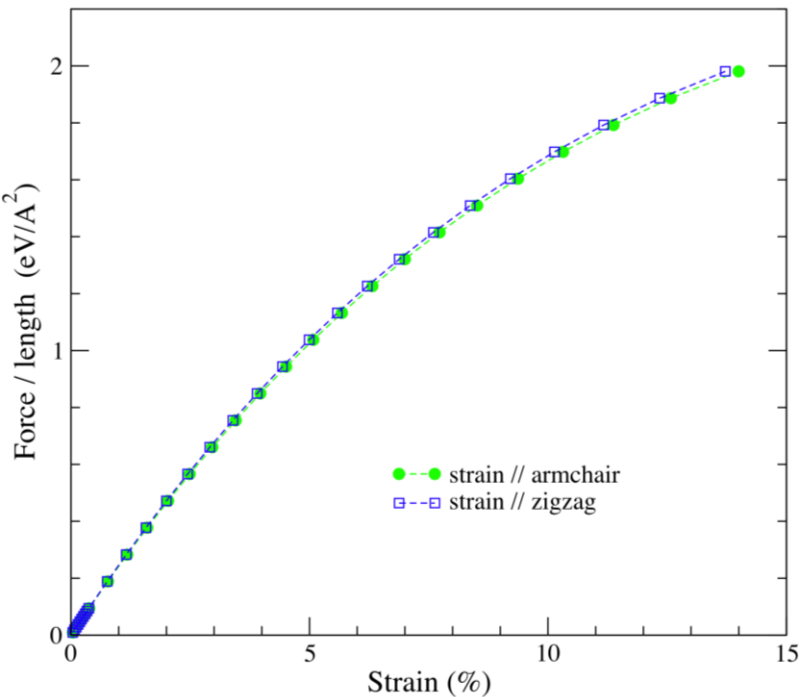
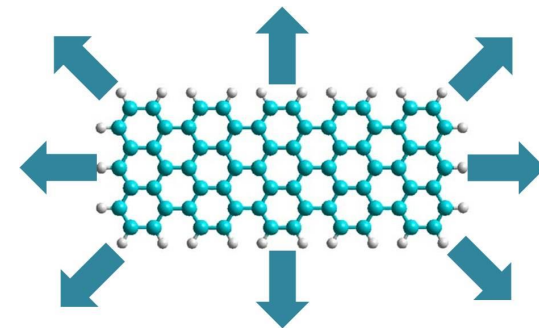
Liu, Ming, Li, *Phys. Rev. B* **76**, 064120 (2007)



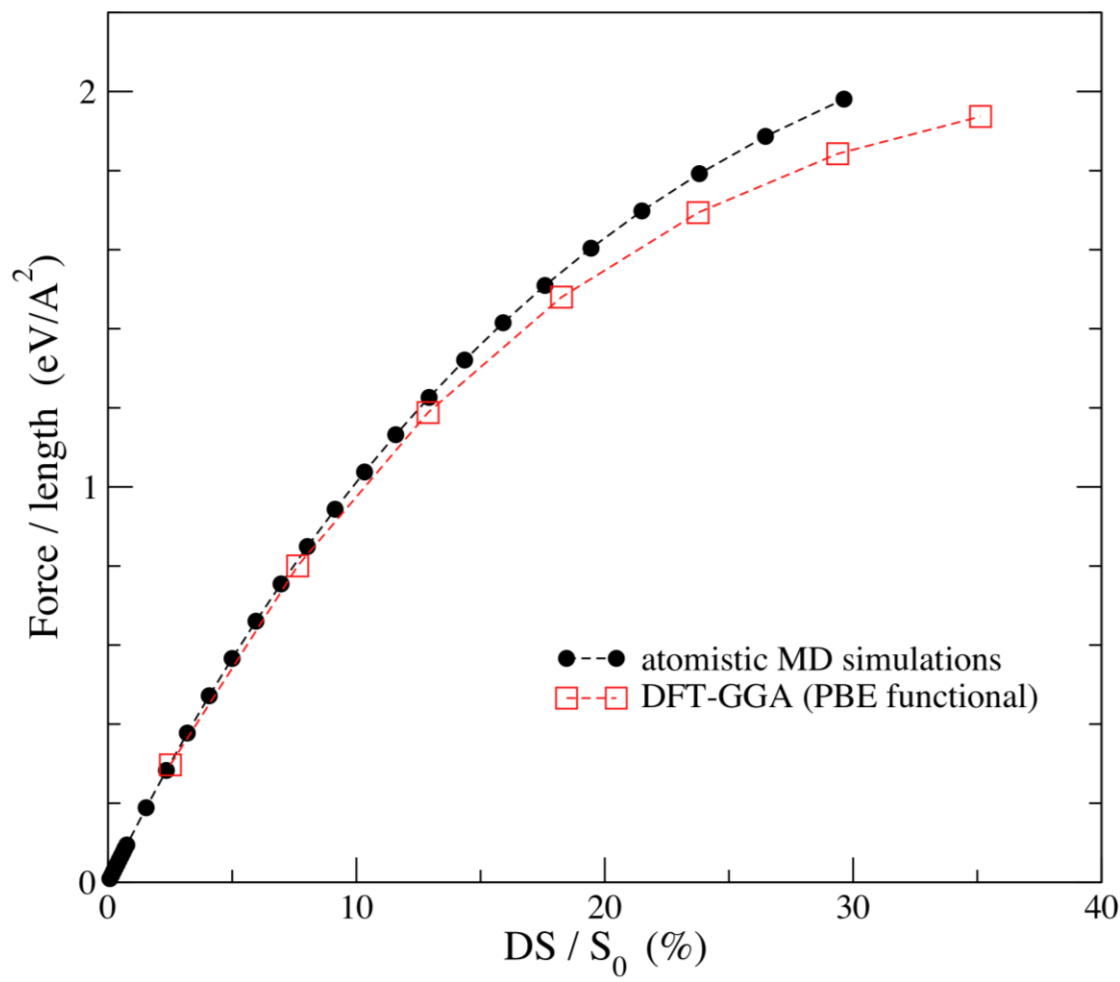
Deformations of bond lengths and angles



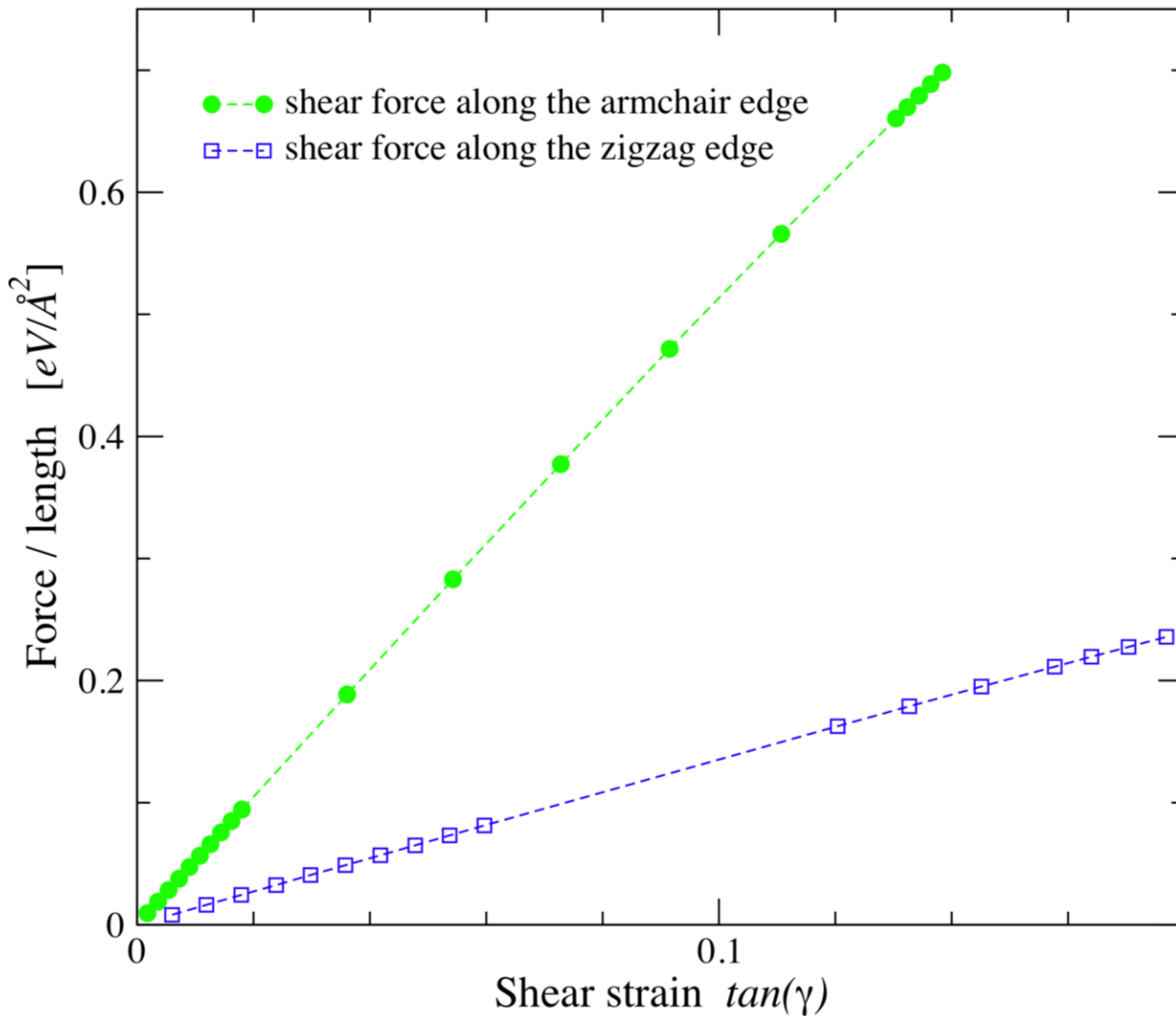
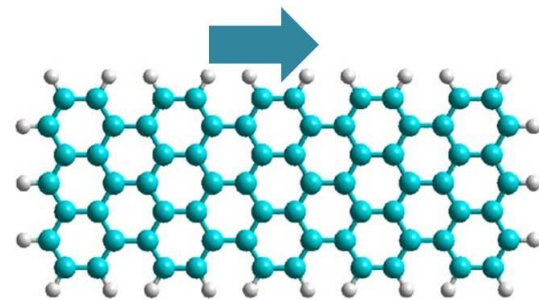
Graphene hydrostatic response



Bulk Modulus
 $B_{2D}=200 \text{ N/m}$



Graphene shear stress response

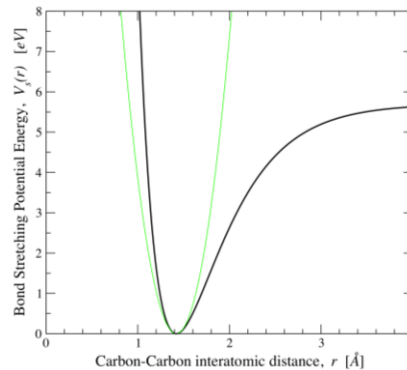
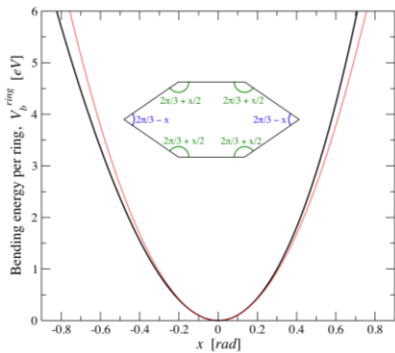
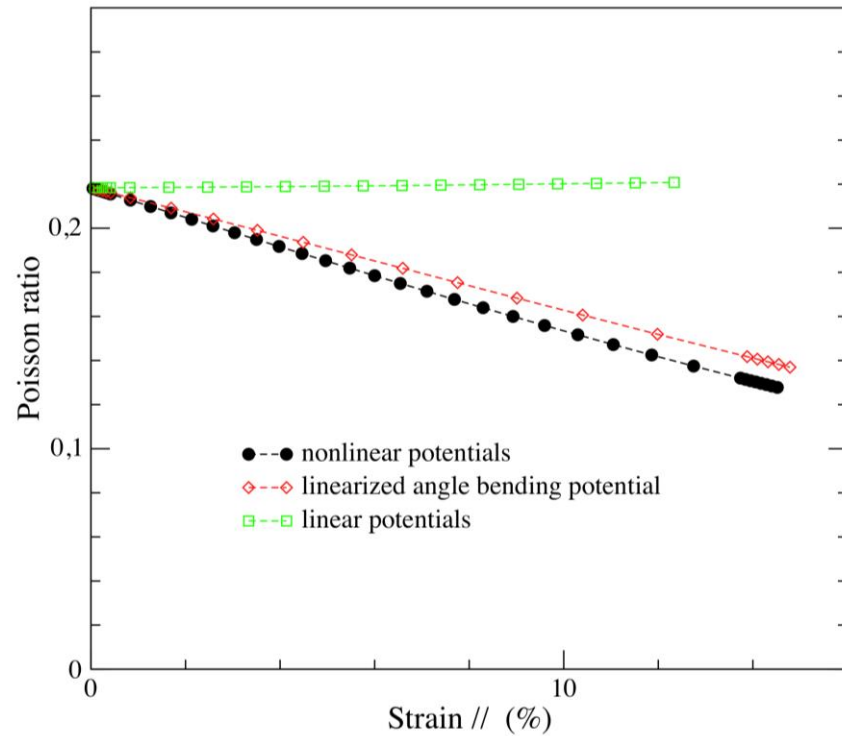
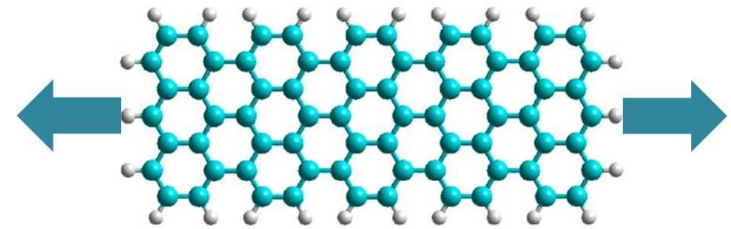
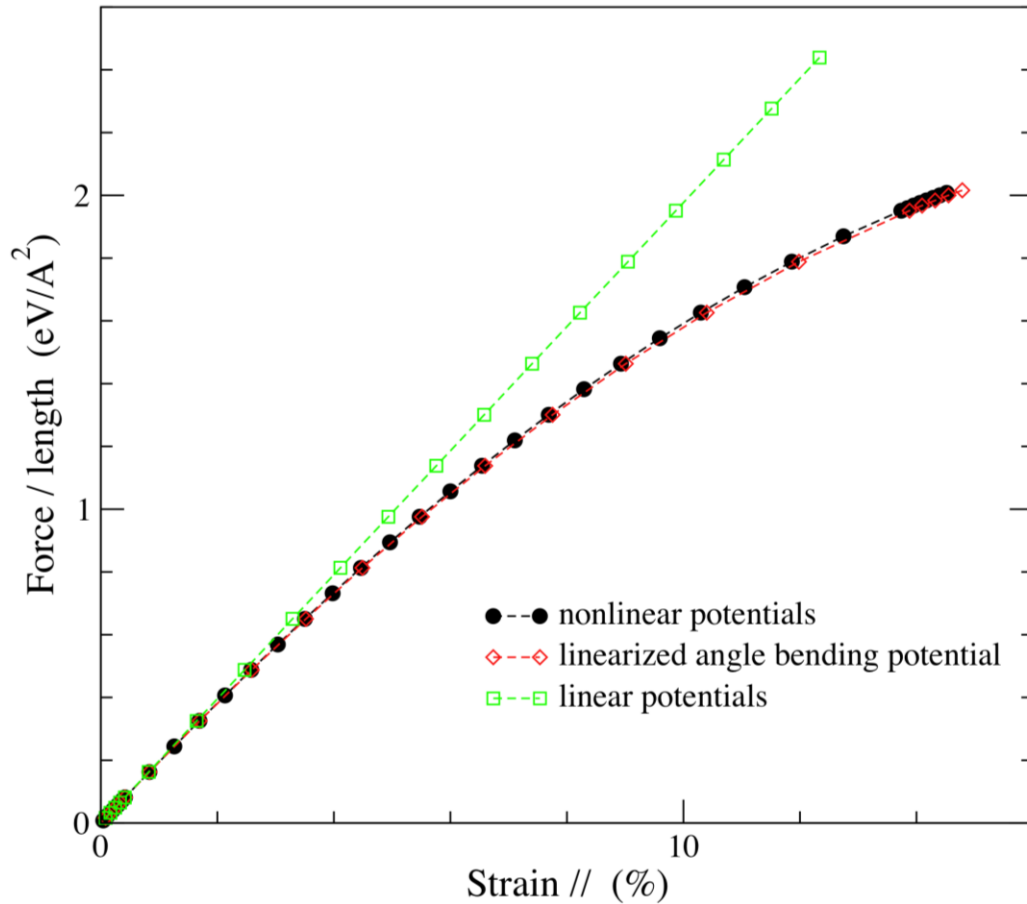


Shear modulus

$$G_{2D}^a = 84 \text{ N/m}$$

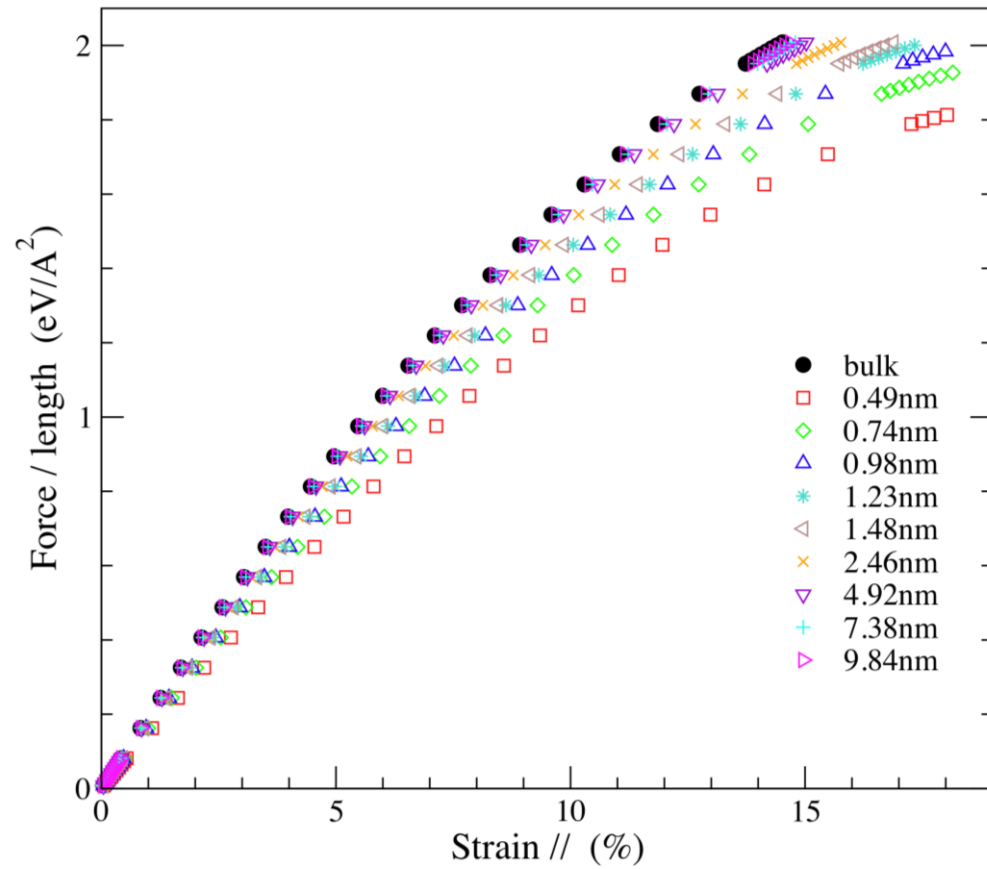
$$G_{2D}^z = 22 \text{ N/m}$$

Comparison with linearized force fields

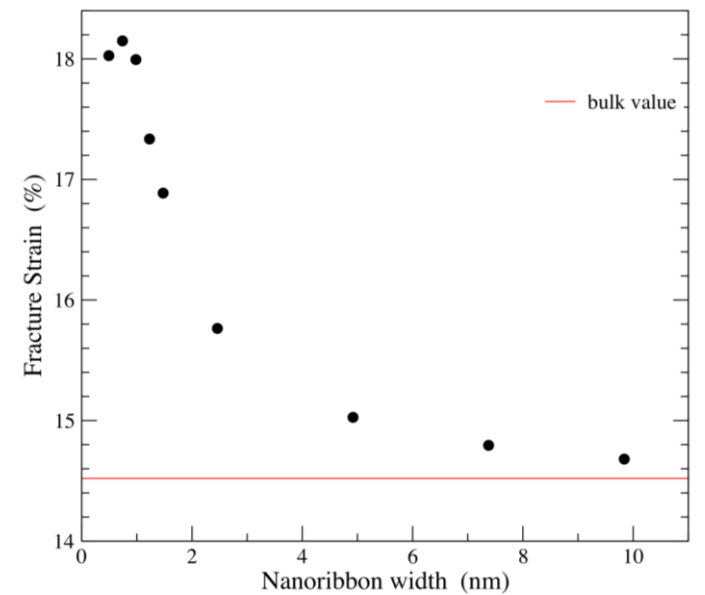
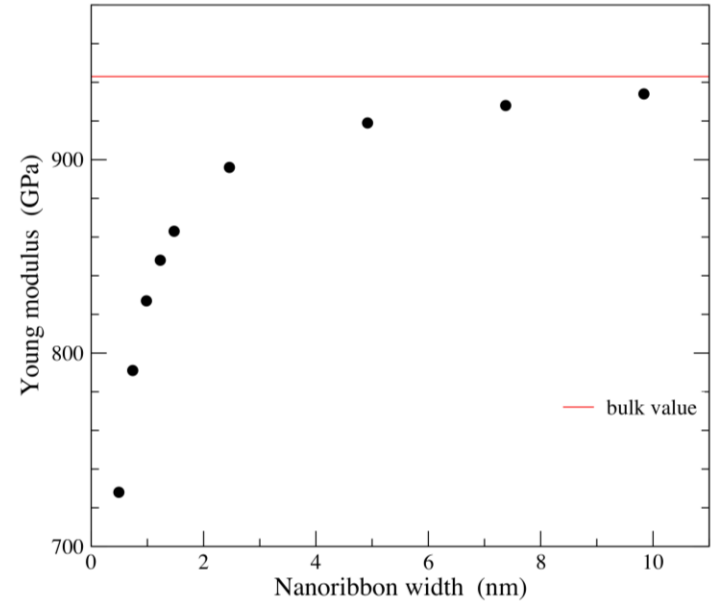
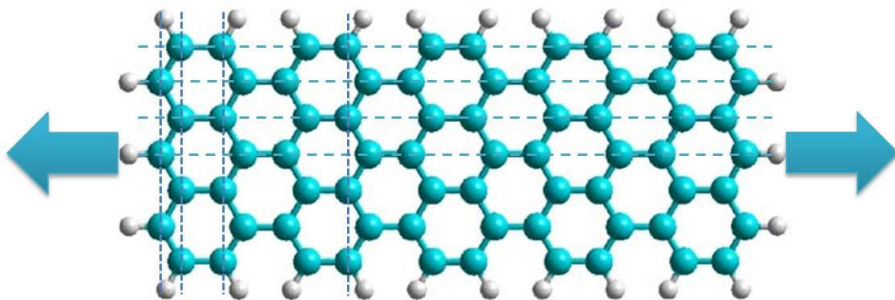


Kalosakas, Lathiotakis, Galiotis, Papagelis,
J. Appl. Phys. **113**, 134307 (2013)

Graphene nanoribbons



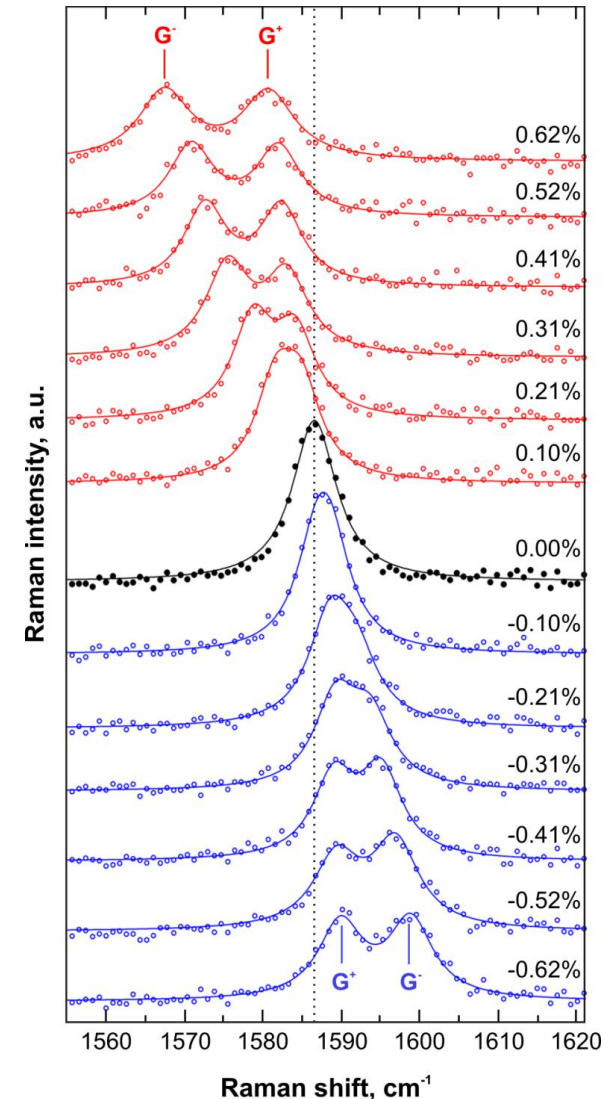
Nanoribbons consisted of 5-60 layers



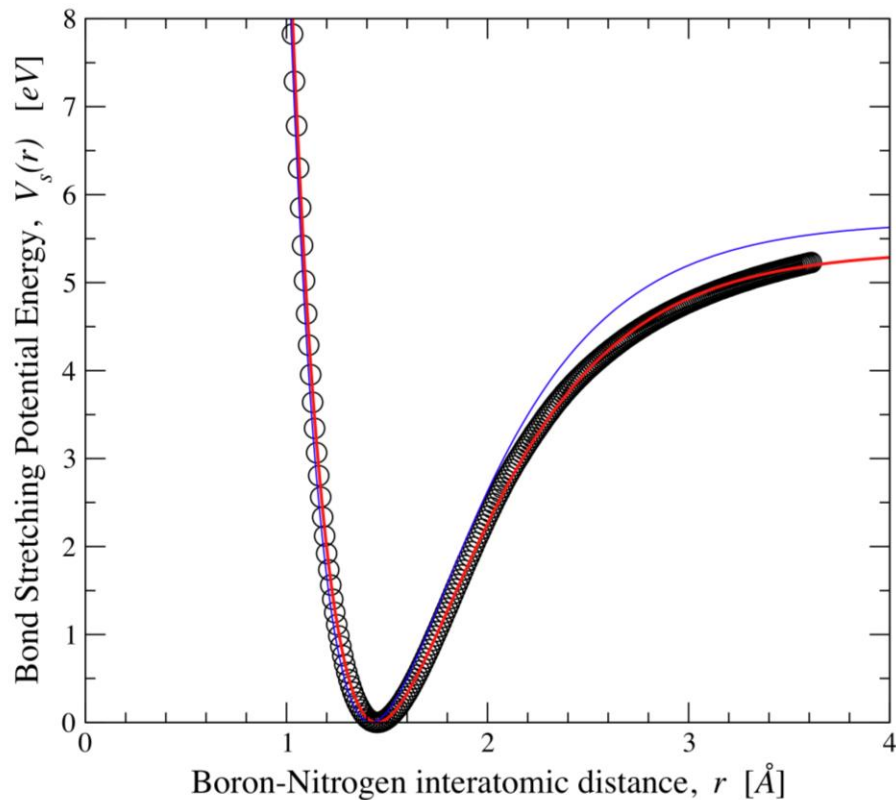
Current projects

- Effect of defects (vacancies, line defects, etc.) in the elastic properties of graphene.
- Phonon Dispersion obtained from MD through the velocity autocorrelation function.
Dynamic response under strain.
Raman G-band splitting.

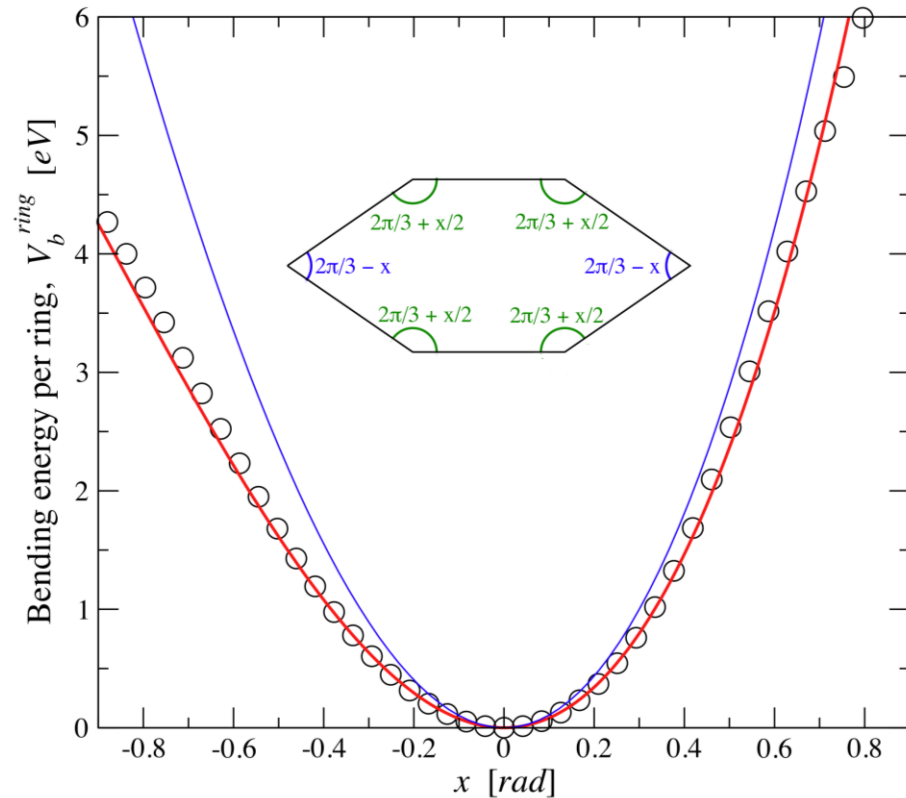
Frank, Tsoukleri, Parthenios, Papagelis, et al.,
ACS Nano **4**, 3131 (2010)



- Force fields and mechanical properties of **Boron-Nitride**



$$V_s(r) = D \left(e^{-a(r-r_0)} - 1 \right)^2$$



$$V_b(\varphi) = \frac{k}{2} \left(\varphi - \frac{2\pi}{3} \right)^2 - \frac{k'}{3} \left(\varphi - \frac{2\pi}{3} \right)^3$$

$$V_b^{ring} = \frac{3}{2} k x^2 + \frac{1}{2} k' x^3$$

Young Modulus $E_{2D} = 260$ N/m

→ $E_{eff} = E_{2D} / 0.33 \text{ nm} = 0.79$ TPa (~80% of graphene)

Summary

- Analytical empirical potentials (bond stretching and angle bending) have been provided for atomistic MD simulations of graphene in 2D.
- The mechanical response of graphene is examined using atomistic MD simulations and DFT calculations
- Various kinds of loads have been investigated (uniaxial stresses, hydrostatic pressure, shear stresses)
- The obtained elastic parameters are in good agreement with experimental as well as other theoretical results

Collaborators

K. Papagelis, C. Galiotis

Dept. Materials Science, Univ. Patras & ICEHT/FORTH, Greece

N.N. Lathiotakis

Theoretical and Physical Chemistry Institute, NHRF, Greece

Thanks \$\$:

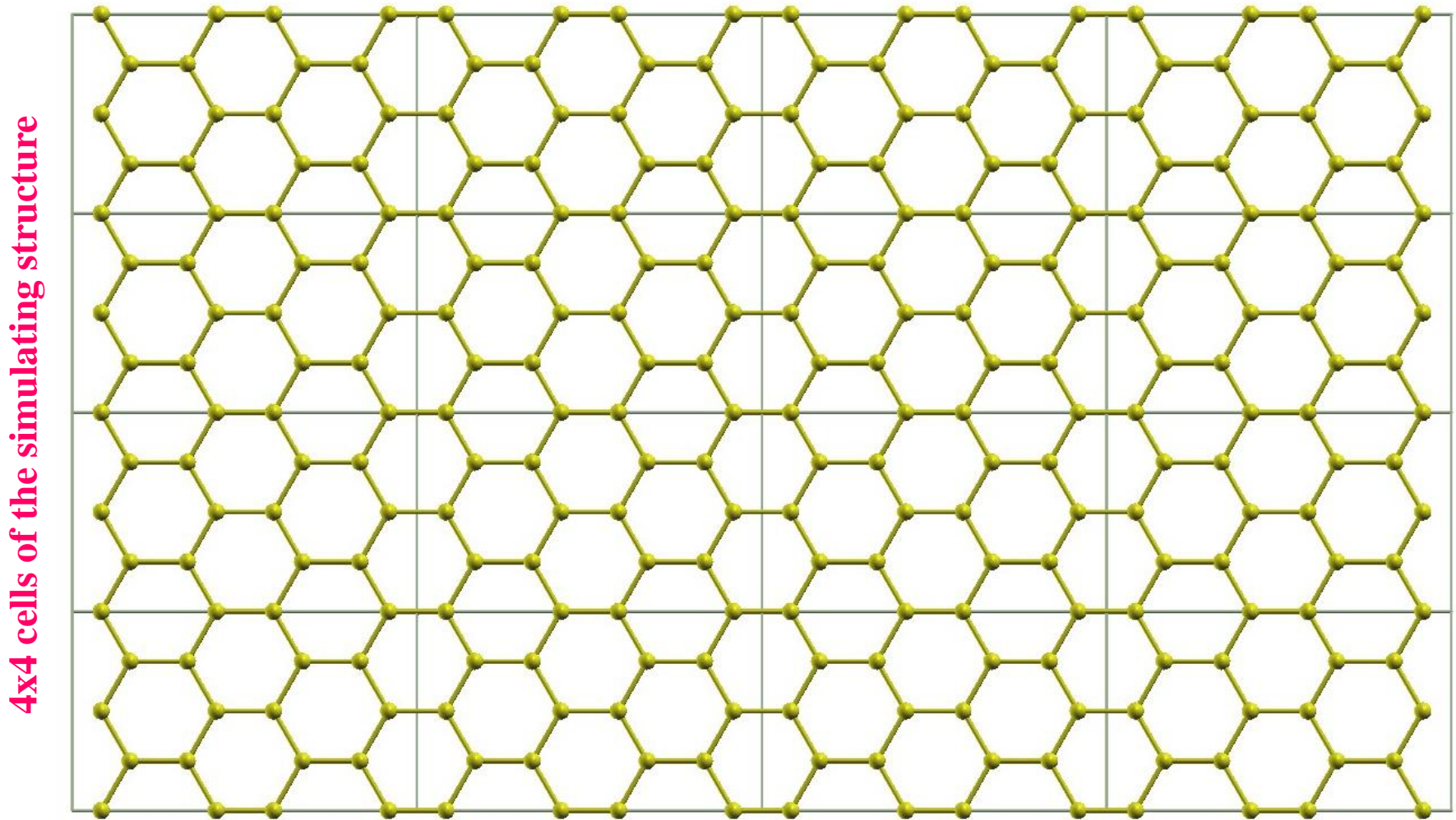
Thales program GRAPHENECOMP,
EU (ESF) & Greek Ministry of Education (ΕΣΠΑ)



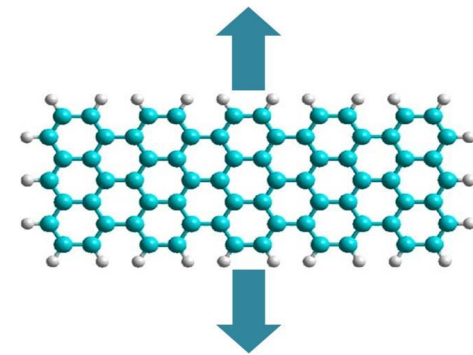
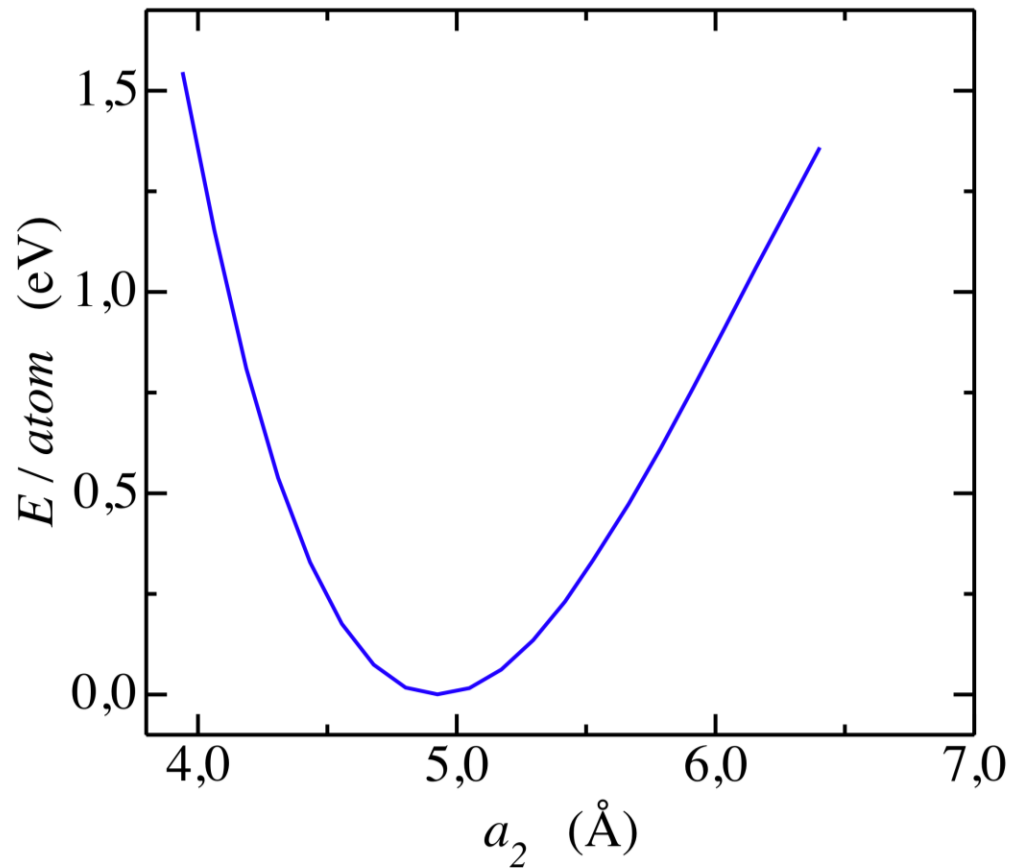
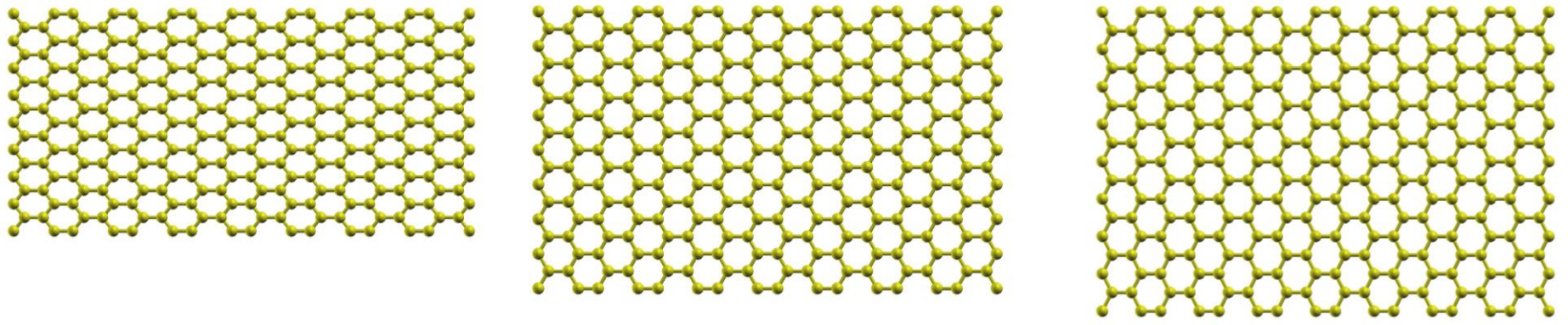
Co-financed by Greece and the European Union

DFT calculations

Generalized Gradient Approximation with PBE functionals (satisfactory description for solids)

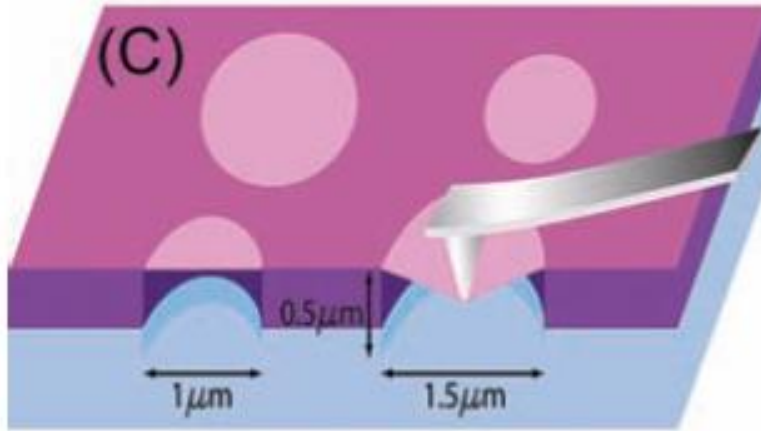


Calculations are performed on one cell (dimensions $a_1 \times a_2$), using periodic boundary conditions. A *fixed strain* is applied on the y direction and the energy of the equilibrated structure is found.

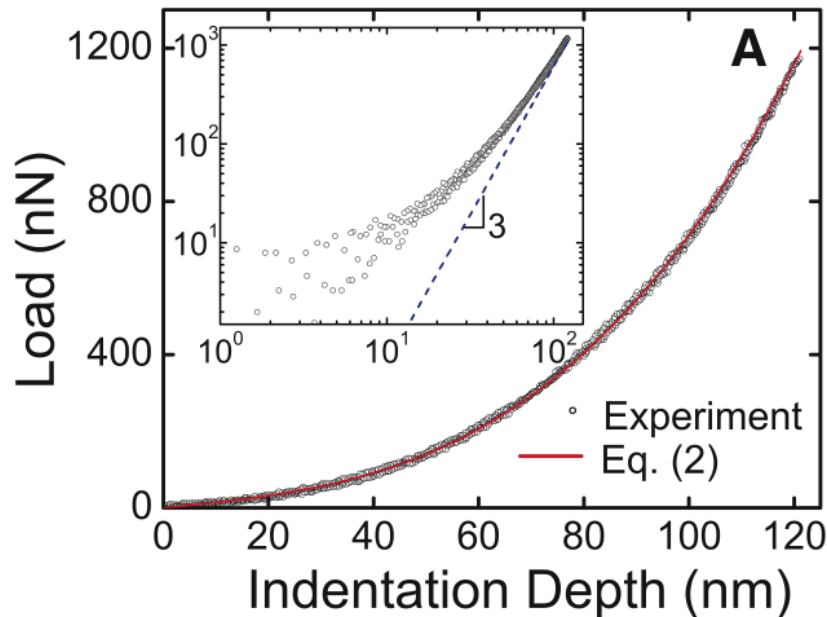


The corresponding force is obtained through the derivative of $E(a_2)$

Graphene as a membrane: bending experiments

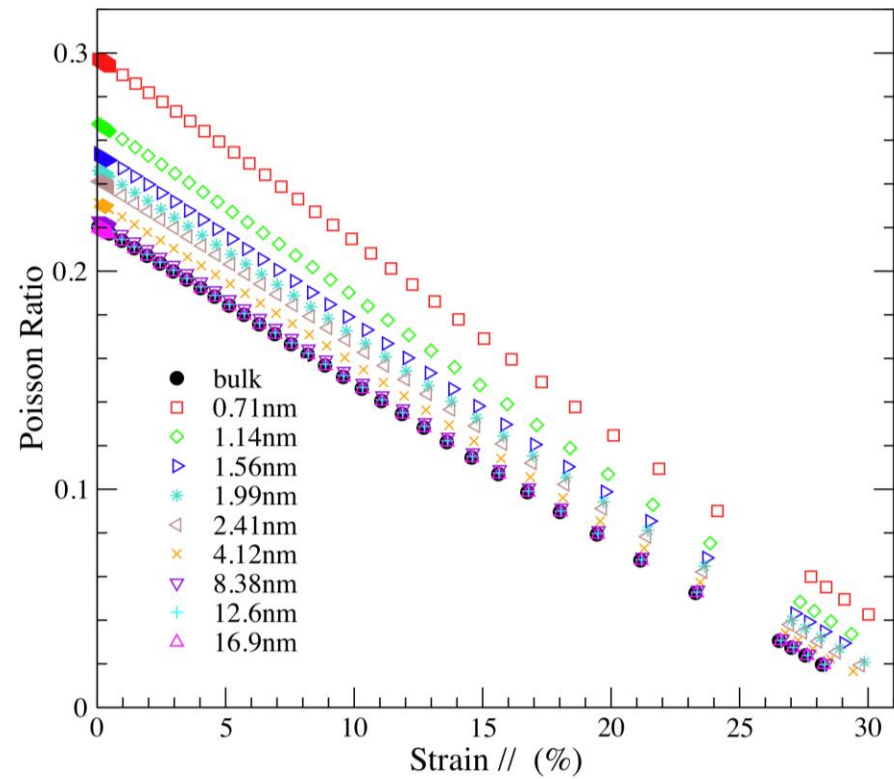
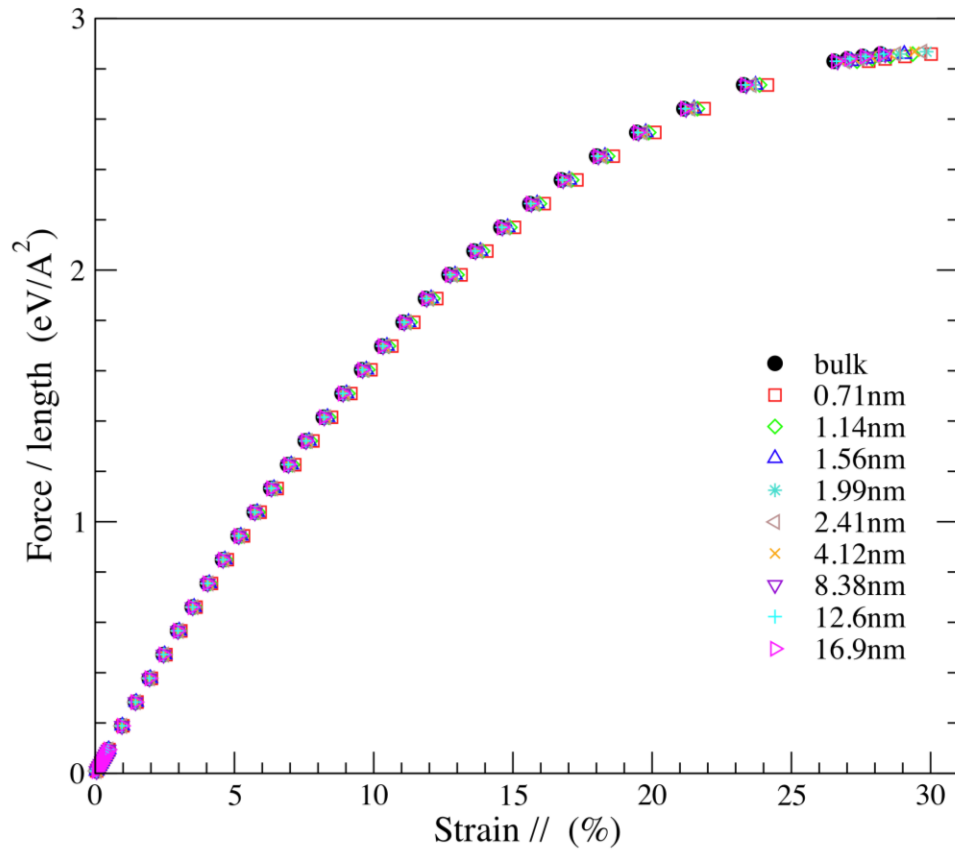


Measurement of the mechanical properties of monolayer graphene suspended over open holes onto SiO₂ substrate using AFM nanoindentation

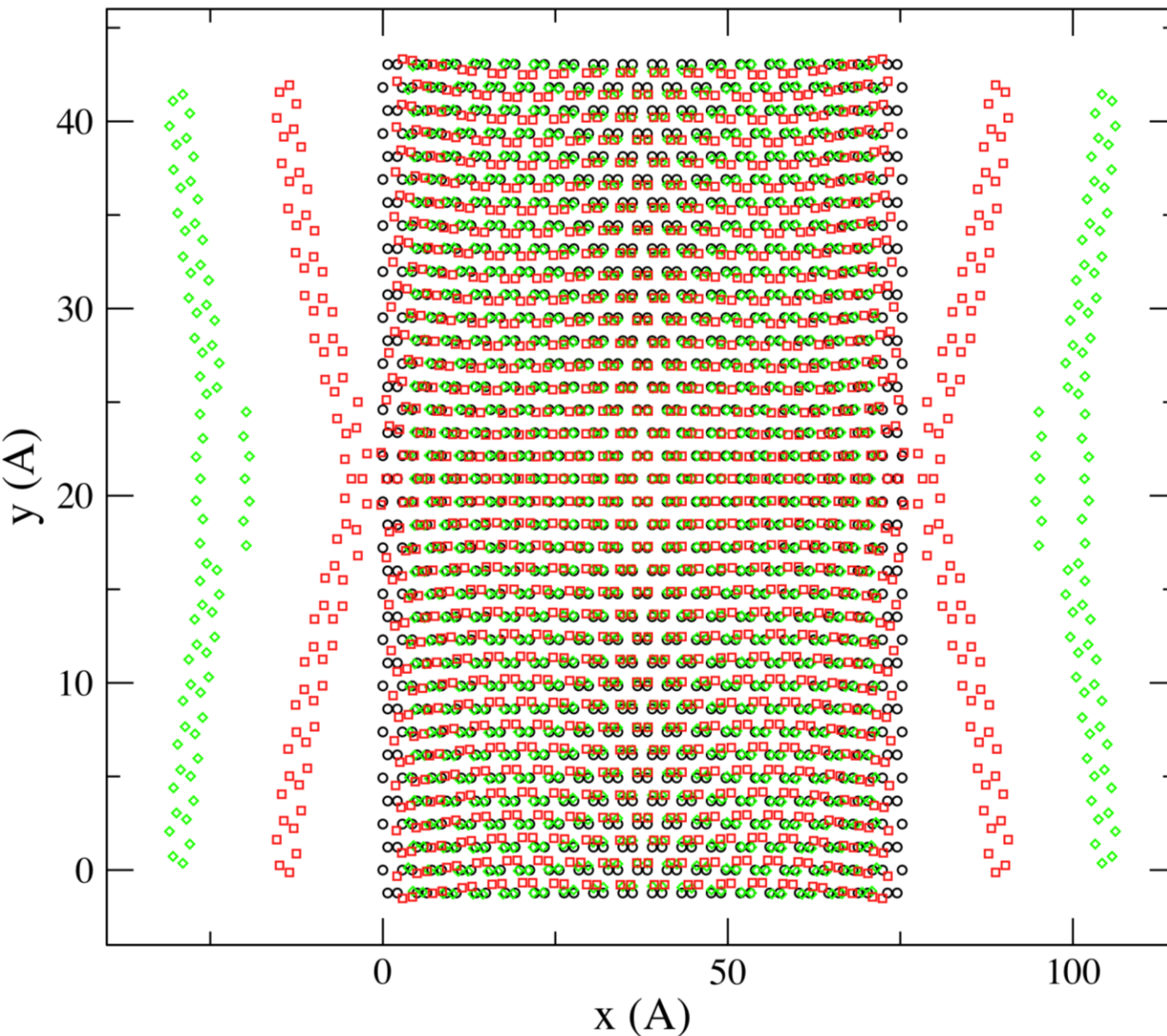
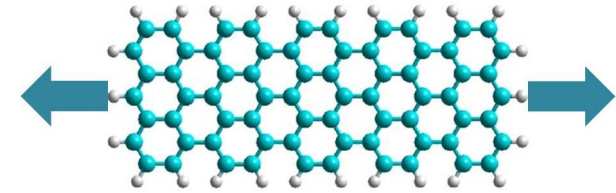


A value of $E=340 \pm 50$ N/m has been derived from fitting an approximate function $F=f(\delta)$ to the experimental data

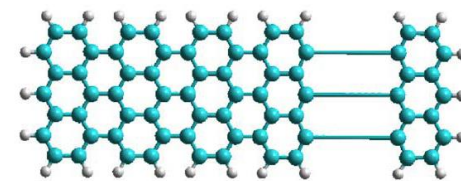
Graphene nanoribbons II



Fracture under uniaxial stress I

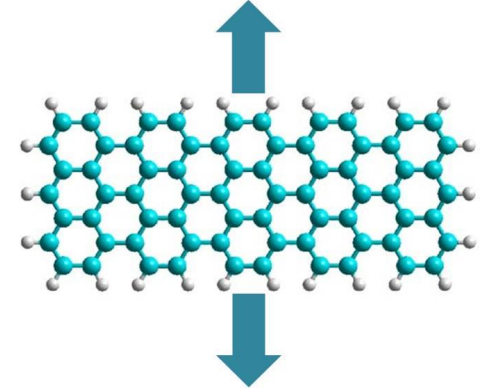
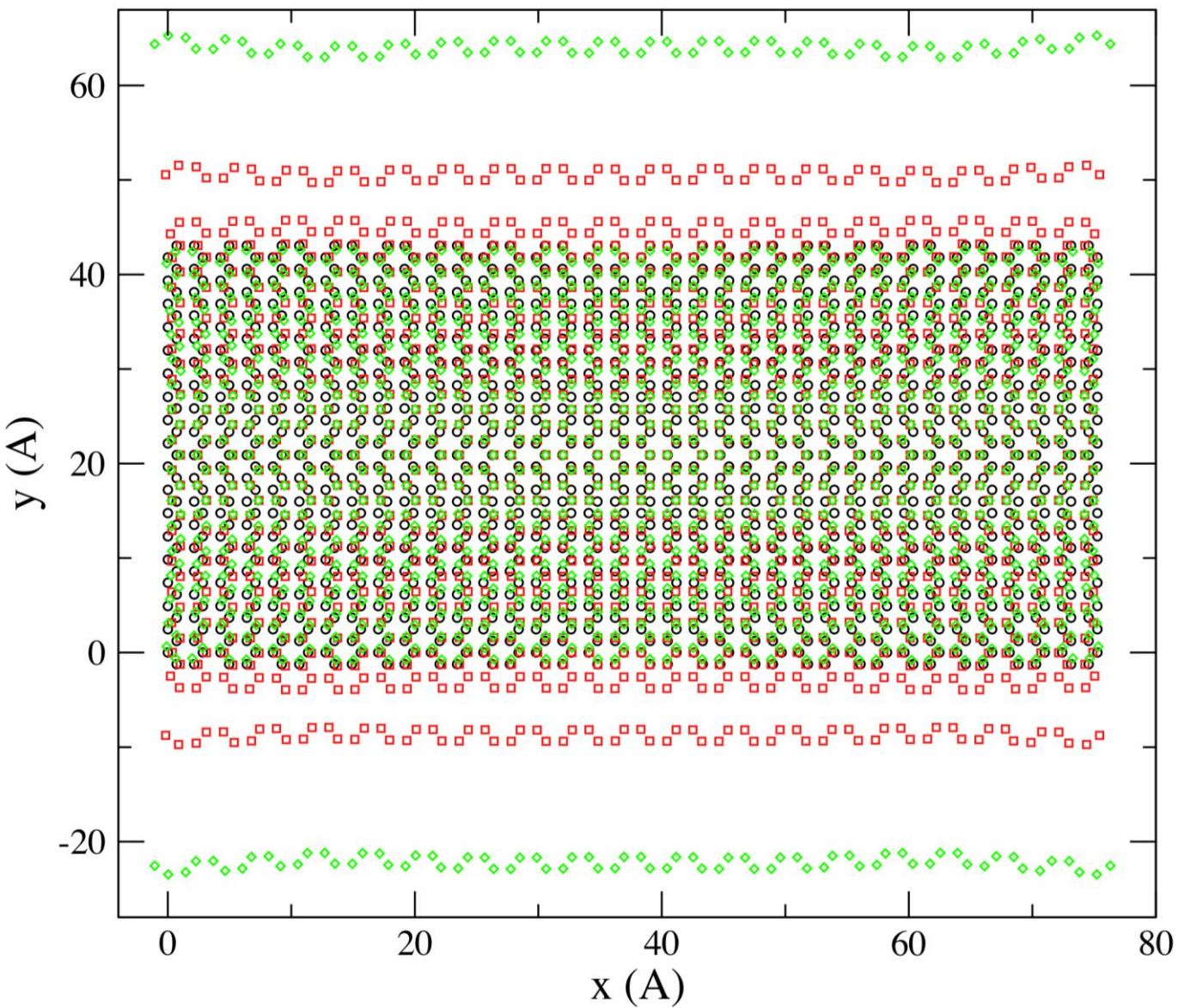


$F = 2.5 \text{ eV/\AA}$

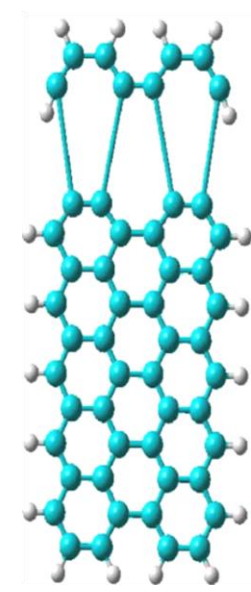


Gao, Hao, *Physica E*
41, 1561 (2009)

Fracture under uniaxial stress II

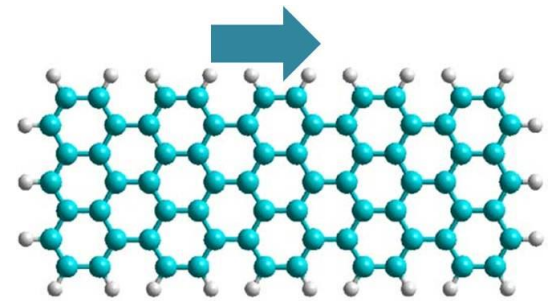
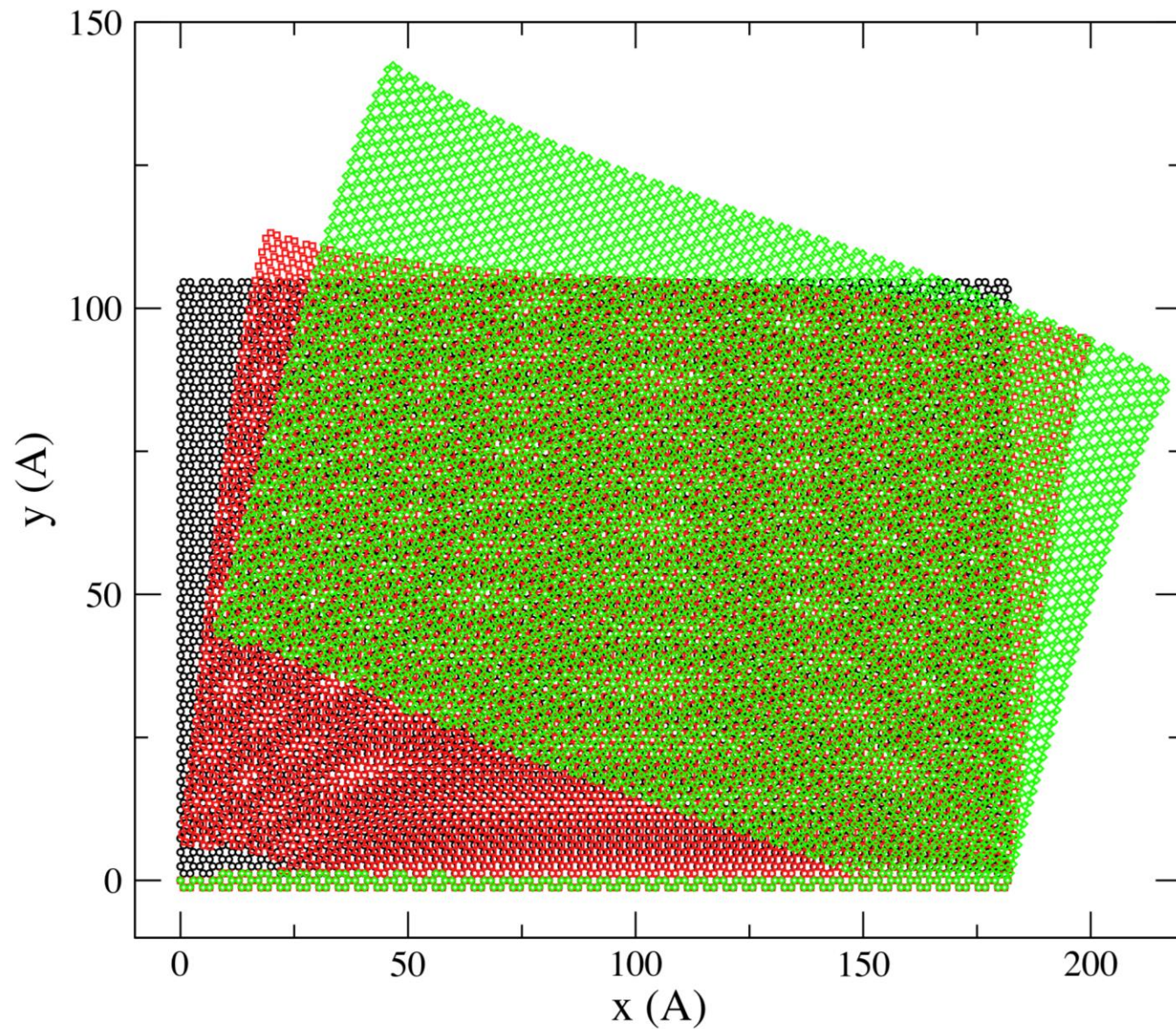


$F = 3.1 \text{ eV/\AA}$



Gao, Hao, *Physica E*
41, 1561 (2009)

Fracture under shear stress



$$F = 0.8 \text{ eV/\AA}$$

Graphene distortion under shear stress

